# $\star \star \star \star \star$ tORMAX AUTOMATIC 



# Installation and Service Manual 1102/ TTX Swing Door Operator TORMAX 1201 Swing Door Operator 

Warning - To reduce the risk of injury of persons - Use this operator only with swing doors.

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## Important Information

## SAFETY/ WARNINGS SYMBOLS

NOTE indicates important information specific to the process or steps being performed.

ELECTRICAL VOLTAGE indicates that electrical voltage is present and that caution should be taken to prevent injury or property damage.


CAUTION indicates failure to follow instructions may result in personal injury and/ or property damage.


OPTIONAL COMPONENTS indicates components that are not installed in all systems.

## $\triangle$

WARNING - Failure to observe the information in this manual may result in personal Injury or damage to equipment. To reduce the risk of injury of persons use this operator only with pedestrian swing doors.
Save these instructions for future reference.

## Installation and Service

Any and all TORMAX equipment must be installed, serviced and inspected by an AAADM Certified technician, to meet the current ANSI A156.10 and/ or ANSI A156.19 standard and any local or state building codes.

The person responsible for the daily operation and maintenance of the system is referred to as "End-User".

It is the technicians responsibility:

1. Review the functions of the equipment with the end-user. Failure to do so, may lead to the improper use, could cause injury to persons and/ or damage to the equipment.
2. Familiarize the end-user with the Daily Safety Check Decal and how to perform the walk test procedures.
3. Illustrate to the end-user how to place the door out of service (turn off power or place in P mode or OFF mode of operation), if the equipment does not perform as described in the Daily Safety Check Decal.
4. Recommend to the end-user to have their equipment inspected annually by an AAADM certified technician.

## Glazing

The glazing material of all doors shall comply with the requirements of ANSI Z97.1, American National Standard Performance Specifications and Methods of Test for Safety Glazing Material Used in Buildings.

## Important Information

## Intended Installation Environment

The 1102/ TTX and the 1201 are non-handed swing door operators that can be used on interior or exterior doors.

The operator is mounted above the door on the inside of the building. Any other use, or any use exceeding this aim, is deemed as not used in accordance with its intended purpose.

The manufacturer will not be liable for damages resulting from such applications or warranty the product. Arbitrary changes to the system will exempt the manufacturer from any liability for damage resulting from this.

The 1102/ TTX is designed as a Low Energy operator to comply with ANSI A156.19 standard.

The 1201 can be utilized as a Low Energy operator and comply with ANSI A156.19 standard, or setup to operate as a Power Operated Pedestrian Door and comply with ANSI A156.10 standard.

Upon completion of the installation the technician should perform an AAADM inspection to ensure that the door complies to the appropriate standard ANSI a156.19 or ANSI A156.10 in which it is setup to operate within.

## Door Operation

The 1102/ 1201 mode of operation is control by a 3-position switch (standard) or a (FCP) Functional Control Panel (optional). The primary mode of operations are:

Off - The door remains in the closed position with lock engaged, but can be opened by the Key Switch activating input.

Automatic - Two-way traffic, typical setting for normal operation. Allows the interior \& exterior sensors, Key switch and safety devices (if applicable) to operate the door.

Hold Open - The door goes to the open position and remains there until the switch is taken out of this position.

Upon a power loss the operation of the 1102/ 1201 operating system will function according to specifications:

Immediate spring closing.
The operator functions as a manual door closure.
Lock function will operate to specification (fail secure/ fail safe).
(2)

Continued operation , if equipped with a battery backup.

## ANSI/ BHMA A156.10, A156.19 standards - Knowing Act Switch

Doors activated by a manual switch must have the switch installed in a location from which the operation of the door can be observed by the person operating the switch. Refer to the latest revision of ANSI/ BHMA A156.10 or A156.19 for location of Knowing Act switch and time delays.

## Important Information

## Operator Applications

The 1102/ 1201 are Surface Applied (SA) operators and are power open and spring close. Basic configuration adjustments will be made with an on-board programming button.

The operator has 2 standard applications:
Outswing - The operator pushes the door open.
Inswing - The operator pulls the door open.
Within each standard application there are important points to know and consider during the installation process.

Outswing: 8-10 lbs. of manual opening force (Low Energy ANSI A156.19) or Knowing Act Door Activation (Power Operated Pedestrian Door ANSI A156.10)
18-20 lbs. of manual opening force ( Power Operated Pedestrian Door ANSI A156.10)

InSwing: 0" reveal, non-handed arm
0 " - 6" reveal, handed arm

## Country Code

The Country code is available in firmware V3.02 and above. The country code provides preset values to aid the technician in installing the door to comply with ANSI Standard A156.19. This does not eliminate the need for an AAADM inspection to be performed for compliance. Additional adjustments may need to be made upon inspection.

## "U" User mode on FCP

The User mode has two options:
UR - Ability to read specific programming parameters without changing the parameter.
UP - Ability to change programming parameters within a limited range.
Refer to programming table for specifics.

(1)
Recommend using " $P$ " programming mode to have full range of adjustments on all parameters.

## Modes of Door Operation

Modes of operation can be selected with either the standard 3-position switch or the optional 6 position Functional Control Panel (FCP).

## The technician will review the appropriate mode switch with the end-user.

Standard:
1102/ 1201



1. OFF - The interior and exterior activators are inhibited after the door reached the fully closed position, if an electric lock is present it will be activated. Door will cycle open, if a signal is sent to the key switch input.
2. AUTOMATIC - Typical setting for normal 2-way traffic operation with interior and exterior activators, key switch input and safety devices operating the door.
3. REDUCED OPERATING - Allows the door to open with a reduced opening width. Activators and safety devices operate the same as automatic mode.
4. EXIT - (1-way traffic) Allows interior activator and key switch inputs to operate the door. The exterior activator input is inhibited from opening the door while the door is closed. When the door is opened/ closing the exterior activator becomes operational and will re-open a closing door.
5. HOLD OPEN - Hold and maintains the door in the open position.

6. (P) MANUAL OPERATION - Allows the door to be used manually without the use of sensors. Push and pull motion applied to the door to open and close the door.

## Components Overview



1 Primary drive TORMAX 1102/1201
2 Secondary drive TORMAX 1102/1201
3 Adjustment of spring force TORMAX 1201 only
4 Adjustment of internal open end stop
5 Shaft $2.48 \mathrm{in} .(63 \mathrm{~mm})$
6 Shaft 3.22 in. ( 82 mm )
7 Shaft 4.84 in. ( 123 mm )
8 Out-Swing (Push) Arm 11.41/ 13.77 in. (290/350 mm)
9 In-Swing (Sliding Pull) Arm 13.77/ 19.68 in. ( $350 / 500 \mathrm{~mm}$ )
10 In-Swing (Slide/ Pull) Arm w/Panic 19.68 in. ( 350 mm ) (not available at this time)

11 Battery unit
12 Header cover
13 Side plate
14 Mounting profile
15 Upgrade modules MDM, PDM, EDM
16 Functional Control Panel (FCP) User interface (Option)
17 On/Off/Hold Open mode of operation switch (Standard)
18 Sync Cable for pairs
19 Shaft retaining bolt

## APPLICATIONS



## On-Board Programming Configuration Tool - Description

## Overview

The On-board programming tool allows the installer to commission the operator without the use of the FCP. If additional changes are needed i.e. time delay, push-n-go the FCP will be required.

The on-board programming tool utilizes the programming button, green \& yellow LEDs and an audible tone device to aid the installer during the commissioning process. During the commissioning process, the LED's flashing sequence and audible tone will continually repeat until a selection is made, then the audible tone and flashing sequence changes for the next parameter selection.

On-board Configuration Tool Familiarization


1 Base door module BDM
2 Programming Button
3 LED GREEN: status display (control system ready for operation) or configuration display.

4 LED YELLOW: error display or configuration display

Programming functions can be launched by means of the programming button.
The GREEN LED supports parameter selection $\quad \rightarrow$ Release the button at the right point in time.
The YELLOW LED indicates the parameter by a series of flashes $\rightarrow$ Press the button at the right point in time.

## Programming Procedure - General

- Keep the programming button depressed. The GREEN LED starts to FLASH at one second intervals for a short time. The number of flashes corresponds to the programming code as in the programming table.
- Release the programming button after the required number of GREEN FLASHES.

Example: Code 5 "Factory Reset" (see below for codes)


## Programming Codes

In order to ensure the safety of the system, please follow the details of the programming steps in the following pages.

Code 1: Commissioning (enter system values, preloads, performs learn)
Code 2: (Consult factory)
Code 3: Detecting/mask out safety features
Code 4: Spring pre-tension parameter (only applicable for TORMAX 1201)
Code 5: Factory reset (Reset all values, excluding operator type)
Code 6: Repeat commissioning (without entering system values, door preloads, performs learn)
Code 7: Preset value 1 = Low Energy (preset values for multiple parameters)

## System Values for the Application

## System Values

After installing the operator determine the 3 system values. Measure the dimensions shown in the illustrations below, select each system value listed below the measurement. Write these numbers down as they are referenced during commissioning.


## Outswing - Low Energy 8-10 lbs Spring Holding Force



1) Determine the handing of the operator according to the door. Note that arrow on operator indicates opening direction of rotation.
2) Locate \& mark output shaft location 12-3/16" from CL of hinge onto door frame
3) Align header at the bottom of the door frame as shown below.
4) Secure header to the wall with appropriate hardware.
5) For Stainless Steel Arm refer to illustration on page 13 for mounting dimensions.


X: Clearance required (distance bottom of header to top of arm)
Y: Distance between bottom of header back plate and centerline of door mounting shoe

| Part No. | Shaft Length | $X$ | $Y$ |
| :--- | :--- | :--- | :--- |
| 141032 (STD) | $3-7 / 32 "(82 \mathrm{~mm})$ | $1-1 / 16^{\prime \prime}(27 \mathrm{~mm})$ | $1-7 / 16^{\prime \prime}(36 \mathrm{~mm})$ |
| 141106 (D.E.) | $3-15 / 16^{\prime \prime}(100 \mathrm{~mm})$ | $1-25 / 32^{\prime \prime}(45 \mathrm{~mm})$ | $2-5 / 32^{\prime \prime}(55 \mathrm{~mm})$ |
| 141205 | $4-27 / 32^{\prime \prime}(123 \mathrm{~mm})$ | $2-11 / 16^{\prime \prime}(68 \mathrm{~mm})$ | $3-1 / 16^{\prime \prime}(78 \mathrm{~mm})$ |

For extended reveals contact TORMAX
6) Locate and mount door arm attachment bracket to the door at $Y$ dimension for shaft used and 14-1/4" from CL of hinge as shown below.
7) Insert shaft/ drive arm (6) into the operator perpendicular to the door as shown below. Tighten shaft bolt to $\mathbf{2 5} \mathbf{f t} / \mathbf{l b s}$.
8) Manually rotate drive arm (8) as shown below $40^{\circ}-45^{\circ}$, check connection point of the two arms to determine how much of the door portion arm (7) may need to be shortened and/ or cut off to connect the two arms.
9) Proceed to page 12 to perform commissioning.


## Outswing - Low Energy 8-10 lbs Commissioning

## Requirements

1. Shaft should be secured into drive unit during mechanical installation.
2. Refer to page $\mathbf{2 2}$ to adjust open door stop.
3. Determine system values for your application based on the illustrations on page 10.

Commissioning


Commissioning Example: $(3)=36$ " door width, $(1)=0-2 "$ reveal, $(1)=$ Standard outswing Arm $113 / 8$. $\qquad$


[^0]MADE AN ERROR DON'T WORRY: To start over Disconnect Power for 10 seconds, Reconnect Power, then Press \& Hold Programming Button and Release after $\mathbf{5}$ Green LED Flashes.

The operator will open 20 degrees stop and beep 2x. Press \& Release programming button. The operator will slowly close and beep $2 x$, next it will slowly fully open and beep $2 x$, then close (beep 1 x ) followed by 5 beeps, and will cycle fully open \& close at normal speed.

Enter Country Code 7 1: (Read Entire Step BEFORE attempting to enter Country Code)

## PERFORM THIS STEP WHILE LOOKING AT BOTH GREEN \& YELLOW LEDS.

Press \& Hold programming button, Release after 7 Green flashes then immediately Press \& Release programming button after 1 Yellow flash.

Programming is complete - for further programming enhancements refer to page 23 or Programming Tables

## Outswing Full Pedestrian 18-20 lbs Spring Holding Force



1) Determine the handing of the operator according to the door. Note that arrow on operator indicates opening direction of rotation.
2) Locate \& mark output shaft location 12-3/16" from CL of hinge onto door frame
3) Align header at the bottom of the door frame and CL of the shaft location as shown below.
4) Secure header to the wall with appropriate hardware.


X: Clearance required (distance bottom of header to top of arm)
Y: Distance between bottom of header back plate and centerline of door mounting shoe

| Part No. | Shaft Length | X | Y |
| :---: | :---: | :---: | :---: |
| 141032 (STD) | 3-7/32" (82mm) | 1-1/16" (27mm) | 1-7/16" (36mm) |
| 141106 (D.E.) | $3-15 / 16^{\prime \prime}$ (100mm) | 1-25/32" (45mm) | 2-5/32" ( 55 mm ) |
| 141205 | 4-27/32" (123mm) | 2-11/16" (68mm) | 3-1/16" (78mm) |

For extended reveals contact TORMAX
5) Locate and mount door arm attachment bracket to the door at $Y$ dimension for shaft used and 16-1/8" from CL of hinge as shown below.
6) Insert shaft/ drive arm into the operator, leave shaft bolt loose until appropriate step during commissioning procedure.
7) Proceed to page 14 to perform commissioning.


## Outswing Full Pedestrian 18-20 Ibs Commissioning

## Requirements

1. Shaft should be loose in the drive unit. Drive arm connected to door and shaft.
2. Determine system values for your application based on the illustrations on page 10.

## Commissioning



Commissioning Example: $(3)=36$ " door width, $(1)=0-2^{\prime \prime}$ reveal, $(1)=$ Standard outswing Arm $113 / 8$. $\square$


Press \& Hold Programming Button, Release after 1 Green LED Flash. The operator will make 1 beep and immediately begin to flash the Yellow LED.

PAUSE
WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 1X, then after 3 yellow flashes, Press \& Release Programming Button

## PAUSE

WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 2X, then after 1 yellow flashes, Press \& Release Programming Button PAUSE

WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 3X, then after 1 yellow flashes, Press \& Release Programming Button

MADE AN ERROR DON'T WORRY: To start over Disconnect Power for 10 seconds, Reconnect Power, then Press \& Hold Programming Button and Release after $\mathbf{5}$ Green LED Flashes.

The operator will open 20 degrees stop and beep 2x. Attach Door Arm to Shaft and Door, place the Door in the Closed Position, and NOW Tighten the shaft to the operator at 25 ft -lbs. REMOVE POWER from Operator and adjust open door stop to desired position, refer to page 22 for adjusting internal Open Door Stop.

RECONNECT POWER (operator beeps 1x), then Press \& Hold programming button \& Release after 6 Green LED Flashes. The operator will open 20 degrees stop and beep $2 x$. Press \& Release programming button. Operator will slowly close and beep $2 x$, next slowly fully open \& beep $2 x$, then close (beep $1 x$ ) followed by 5 beeps, and will cycle fully open \& close at normal speed.

Commissioning is complete for High Energy Applications. For Low Energy application complete the last step below Program the country code into the controller. For additional programming refer to page 23 or Programming Tables.

Enter Country Code 7 1: (Read Entire Step BEFORE attempting to enter Country Code)
PERFORM THIS STEP WHILE LOOKING AT BOTH GREEN \& YELLOW LEDS.
Press \& Hold programming button, Release after 7 Green flashes then immediately Press \& Release programming button after 1 Yellow flash.

## Inswing (Pull) Arm 0" Reveal Installation



1) Determine the handing of the operator according to the door. Note that arrow on operator indicates opening direction of rotation
2) Locate \& mark output shaft location 12-3/16" from CL of hinge onto door frame as
3) Determine header mounting height $=X$. See below.
4) Bolt header to the wall with appropriate hardware.

## Standard Aluminum Arm



X: Mounting height (distance bottom of header to top of door)

| Part No. | Shaft Length | $X$ |
| :--- | :--- | :--- |
| 141032 (STD) | $3-7 / 32 "[82 \mathrm{~mm}]$ | $1-3 / 44^{\prime \prime \prime}(44 \mathrm{~mm}]$ |
| 141205 | $4-27 / 32 "[123 \mathrm{~mm}]$ | $3-3 / 8 "[86 \mathrm{~mm}]$ |
| 141020 | $2-5 / 8^{\prime \prime}[67 \mathrm{~mm}]$ | $1-5 / 32 "[29 \mathrm{~mm}]$ |

For extended reveals contact TORMAX
5) Locate and mount door arm slide track onto the door at 4 " from C/L of pivot, mounting holes $5 / 8$ " from top of the door as shown below.
6) Insert shaft/ drive arm into the operator, leave shaft bolt loose until appropriate step during commissioning procedure.
7) Proceed to page 16 to perform commissioning

Stainless Steel Arm


Butt Hingle or Offset Pivot


## Inswing (Pull) Arm 0" Reveal Commissioning

## Requirements

1. Shaft should be loose in the drive unit. Drive arm connected to slide track and shaft.
2. Determine system values for your application based on the illustrations on page 10.

Commissioning


Commissioning Example: $(3)=36$ " door width, $(1)=0-2^{\prime \prime}$ reveal, $(1)=$ Standard inswing Arm $113 / 8$.


Press \& Hold Programming Button, Release after 1 Green LED Flash. The operator will make 1 beep and immediately begin to flash the Yellow LED.

PAUSE
WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP $1 \mathbf{X}$, then after 3 yellow flashes, Press \& Release Programming Button

PAUSE
WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 2X, then after 1 yellow flashes, Press \& Release Programming Button PAUSE

WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP $3 X$, then after 4 yellow flashes, Press \& Release Programming Button

MADE AN ERROR DON'T WORRY: To start over Disconnect Power for 10 seconds, Reconnect Power, then Press \& Hold Programming Button and Release after 5 Green LED Flashes.

The operator will open 20 degrees stop and beep $2 x$. Attach Door Arm to Slide Track and Shaft, place the Door in the Closed Position, and NOW Tighten the shaft to the operator at 25 ft -lbs. REMOVE POWER from Operator and adjust open door stop to desired position, refer to page 22 for adjusting internal Open Door Stop.

RECONNECT POWER (operator beeps 1x), then Press \& Hold programming button \& Release after 6 Green LED Flashes. The operator will open 20 degrees stop and beep $2 x$. Press \& Release programming button. Operator will slowly close and beep $2 x$, next slowly fully open \& beep $2 x$, then close (beep $1 x$ ) followed by 5 beeps, and will cycle fully open \& close at normal speed.

Commissioning is complete for High Energy Applications. For Low Energy application complete the last step below Program the country code into the controller. For additional programming refer to page 23 or Programming Tables.

Enter Country Code 7 1: (Read Entire Step BEFORE attempting to enter Country Code)
PERFORM THIS STEP WHILE LOOKING AT BOTH GREEN \& YELLOW LEDS.
Press \& Hold programming button, Release after $\mathbf{7}$ Green flashes then immediately Press \& Release programming button after $\mathbf{1}$ Yellow flash.

## Inswing (Pull) Arm 0-6" Reveal Installation



1) Determine the handing of the operator according to the door. Note that arrow on operator indicates opening direction of rotation.
2) Locate \& mark output shaft location as shown below from CL of hinge or pivot onto door frame.
3) Mark header mounting height of $11 / 8$ " from the top of the door as shown below.
4) Secure header to the wall with appropriate hardware.
5) Locate and mount door arm slide track onto the door at $33 / 4$ " from bottom of the header and at the dimensions listed below for the application.
6) Insert shaft/ drive arm into the operator, leave shaft bolt loose until appropriate step during commissioning procedure.
7) Proceed to page 18 to perform commissioning.

Butt Hinge


Center Pivot


## Inswing (Pull) Arm 0-6" Reveal Commissioning

## Requirements

1. Shaft should be loose in the drive unit. Drive arm connected to door and shaft.
2. Determine system values for your application based on the illustrations on page 10.

Commissioning


Commissioning Example: $(3)=36$ " door width, $(1)=2-4$ " reveal, $(1)=$ Extended inswing Arm B. | 3 | 2 | 6 |
| :--- | :--- | :--- |



Press \& Hold Programming Button, Release after 1 Green LED Flash. The operator will make 1 beep and immediately begin to flash the Yellow LED.

> PAUSE

WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 1X, then after 3 yellow flashes, Press \& Release Programming Button PAUSE

WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 2X, then after 2 yellow flashes, Press \& Release Programming Button PAUSE

WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP $3 X$, then after 6 yellow flashes, Press \& Release Programming Button

MADE AN ERROR DON'T WORRY: To start over Disconnect Power for 10 seconds, Reconnect Power, then Press \& Hold Programming Button and Release after $\mathbf{5}$ Green LED Flashes.

The operator will open 20 degrees stop and beep 2x. Attach Door Arm to Slide Track and Shaft, place the Door in the Closed Position, and NOW Tighten the shaft to the operator at 25 ft -lbs. REMOVE POWER from Operator and adjust open door stop to desired position, refer to page 22 for adjusting internal Open Door Stop.

RECONNECT POWER (operator beeps 1x), then Press \& Hold programming button \& Release after 6 Green LED Flashes. The operator will open 20 degrees stop and beep $2 x$. Press \& Release programming button. Operator will slowly close and beep $2 x$, next slowly fully open \& beep $2 x$, then close (beep $1 x$ ) followed by 5 beeps, and will cycle fully open \& close at normal speed.

Commissioning is complete for High Energy Applications. For Low Energy application complete the last step below Program the country code into the controller. For additional programming refer to page 23 or Programming Tables.

Enter Country Code 7 1: (Read Entire Step BEFORE attempting to enter Country Code)
PERFORM THIS STEP WHILE LOOKING AT BOTH GREEN \& YELLOW LEDS.
Press \& Hold programming button, Release after 7 Green flashes then immediately Press \& Release programming button after 1 Yellow flash.

## Double Egress Application Installation



1) Determine the handing of the operators according to the door. Note that arrow on operator indicates opening direction of rotation.
2) Locate \& mark output shaft locations as shown above, for both operators.
3) Determine header mounting height. If both operators are in a single header then mount the operators at 1-1/8"
4) Secure header to the wall with appropriate hardware.
5) Locate and mount door arm and slide track onto the doors at dimensions listed above.
6) Insert shaft/ drive arms into the operators, leave shaft bolts loose until appropriate step during commisioning procedure.
7) Proceed to page 20 to check or connect sync cable and additional wiring.

In-Swing Operator

Out-Swing Operator


## Pair \& Double Egress Application Wiring

1. Determine which operator will be the primary drive as this will have the 3 -position switch connection.

The FCP is an option in place of the 3-position and will be connected to the primary drive with appropriate module, Exterior Door module EDM or Programming Interface module PIM.
2. Check and/ or install jumpers between GND pin 1 - IN 1 pin 2 and GND pin 1 -IN2 Pin 3 in place of the 3-position switch on the secondary drive as shown below.


## Secondary Drive


3. Install Multi Door Module MDM-B into each operator.

4. Connect Sync cable (US801886) to both drives Multi Door Module MDM - B as shown below.

Wiring of Sync Cable

(I) Do not apply primary power to the drive units until the appropriate step.

Proceed to page 21.

## Pair \& Double Egress Application Commissioning

## Requirements for Both Operator

1. An MDM module Installed in both operators along with optional modules (PIM, EDM, PDM) prior to start-up. Refer to Technical Specifications section.
2. Refer to application's commissioning page to determine shaft condition. (loose or secured)
3. Determine system values based on the illustrations on page 10.

|  |  |  | Primary |
| :--- | :--- | :--- | :--- |
|  |  |  | Secondary |

Commissioning

1. Connect primary power 120 vAC to Primary operator first, then the Secondary operator this will configure the operators (Primary/ Secondary).

2. Commissioning sequence - Perform Commissioning of Primary operator first, then perform Commissioning of Secondary operator.
3. Refer to the applications Commissioning page:

Outswing 8-10 lbs. Spring Holding force (Low Energy) Refer to page 11 for securing the Shaft \& Arm position, Page 12 for commissioning


Outswing 14-15 lbs. Spring Holding Force (Full Power) - Page14

Inswing 0" Reveal - Page 16


Inswing 0-6" Reveal - Page 18

4. Adjustments:

Double egress/ simultanious pairs - Turn OFF delayed activation of secondary operator = Code 830

Frequently used adjustments are listed on page 23

## Adjustments - Door Stop/ 1201 Spring Tension

Adjusting Internal Open Door Stop
Determine opening angle required for application adjust internal stop accordingly.

(!) An external door stop may be needed depending on application (abuse, excessive wind...).

Mechanical Spring Tension Adjustment (Optional ) - 1201 ONLY
(I) Adjust spring tension to close the door in adverse applications with no primary power applied.


1. Adjust spring tension on the operator, note Code for the adjustment made. Example 20mm = Code 5.

Number of Flashes

| 0 | 5 | 10 | 15 | 20 | 25 | 30 | 35 | 40 | Tension length in mm |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{1}^{*}$ | $\mathbf{2}$ | $\mathbf{3}$ | 4 | 5 | 6 | 7 | 8 | 9 | Code |

2. Programming spring tension adjustment with On-Board Button:
(Read Entire Step BEFORE attempting to enter Country Code)

## PERFORM THIS STEP WHILE LOOKING AT BOTH GREEN \& YELLOW LEDS.

Press \& Hold programming button, Release after 4 Green flashes then immediately Press $\&$ Release programming button after \# Yellow flashes for code value .
3. Changing the spring tension will require a commissioning process to be performed with On-Board button Code 6 Green flashes or entering Code 021 with FCP.

## Adjustments - Frequently Used

## Adjustments

Country Code configures the operator for Low Energy application for more details refer to page 31. To set the Country code 7 with On-Board Button follow the instructions below:

Enter Country Code 7 1: (Read Entire Step BEFORE attempting to enter Country Code)

## PERFORM THIS STEP WHILE LOOKING AT BOTH GREEN \& YELLOW LEDS.

Press \& Hold programming button, Release after 7 Green flashes then immediately Press \& Release programming button after 1 Yellow flash.

Additional adjustments may be made after commissioning which require a PIM Program Interface module and an FCP. If the door requires or is equipped with an EDM Exterior Door Module then a PIM in not needed.

Listed below are the most common adjustments. For a complete list of adjustments refer to the Programming Charts.
*Hold open time = Code 10?
*Push-N-Go OFF = Code 860
*Close Check Force OFF = Code 320
**Power Close for Lock Release ON = Code 581
**Delay Time to Open = Code 591
Power Pulse when Opening = Code 43? Over come wind stack pressure or lock
*Double egress/ simultanious pairs = Code 830
Turn OFF delayed activation of secondary operator for pair applications.
Detecting/ mask out safety functions details on page 31:
On-Board Button = Code 3
FCP = Code 023
Repeat commissioning without system values details on page 31.

$$
\text { On-Board Button = Code } 6
$$

Power Assist in AUTO ON = Code 862
Power Assist Hold open Time = Code 150

* Adjustments have been changed by entering Country code 7.
** Adjustment 591 needs to be made in conjunction with 581.


## Testing

 putting the door into service and handing it over to the End-User.
## Slim Line - Header Preparation



## Slim Line - Application Illustrations



## Programming with the FCP - Overview

Programming with the Functional Control Panel (FCP) refer to T1757 in Technical Specification section requires at least one of the following modules to be installed PIM shown below refer to T1691 or EDM T1638.


## The Functional Control Panel (FCP) has 2 function levels:

Level 1 - End user

- Select operating modes
- Display three-digit fault codes.
- Access protected eliminates unauthorized programming.

Level 2 - AAADM Certified Technician

- "U" = User readable parameter - allows technician to read specific parameters. See programming chart for parameters.
- Access protection, access code (111)
- Programming door system to comply with the current ANSI A156.10 or ANSI A156.19 standard.
- Displays currently set parameter.
- 10 min time out after the last programming entry is made. The technician will be required to enter the access code (111) to make further adjustments.


## Programming with the FCP - Overview

(1)Button 1 - Changes the number or letter by increments of one (0,1,2,3-9,a,b,c,...back to 0 ) Button 2 - Confirms/ enter displayed number or letter into the control.

1) Start Access Code

2) Entering Access Code 111
 out you will be able to enter a parameter.
3) Start Programming Level


## Programming with the FCP

Example 1: Enter access code 111

| Press both buttons simultaneously a continue to press both buttons and a | Display on FCP | will display |
| :---: | :---: | :---: |
|  | U |  |
|  | C | will display, release both buttons |
| *Press button 2 and | 0 | will display |
| Press button 1 to display | 1 | Press button 2 to confirm/ enter |
|  | 0 | Will display |
| Press button 1 | 1 | Press button 2 to confirm/ enter |
|  | 0 | Will display |
| Press button 1 | 1 | Press button 2 to confirm/ enter |
|  | P | Will display,operator is ready to b |

Example 2: Enter code 103 to adjust the Hold Open time for 2 sec


Hold Open time for Automatic 1 is now set for 2 sec

Within 10 minutes you can enter the programming mode by pressing both keys simultaneously and $P$ will display. If no further adjustments are made after 10 minutes the FCP will time out and require access code re-entry. Repeat example 1.

After confirming/ entering the 2nd number of the code, the 3rd flashing value (number or letter) of the code is the parameter setting. If the value is confirmed the FCP will rapidly flash for 1 sec then display " $P$ " again. displaying the mode of operation.

## Commissioning with FCP

## Requirements:

1. Programming with the Functional Control Panel (FCP) requires at least one of the following modules to be installed PIM refer to T1691 or EDM T1638. If optional modules (MDM, PDM) are required install prior to start-up.
2. The drive arm is connected to the door and the drive arm shaft has not been tightened, exception outswing 8-10 lbs .
3. Pair of doors - the sync cable and additional wiring outlined on page 20 has been completed.
4. Connect safety sensors to door control, adjust in accordance to manufacturer's specifications.

## Start-up:

(1)
Double egress/ simultanious pairs applying power in the wrong sequence will cause configuration problems.

1. Apply primary power to the operator, for pair of doors apply power to the Primary operator first, then to the Secondary operator.

2. Enter System Parameters - Refer to page 10 to determine values. Complete sequence for Primary operator first.


## Enter Code 06? Door width

Enter Code 07? Distance of drive arm
Enter Code 08? Sliding lever length

## 3. Arm Preload

Enter Code 021 operator will rotate 20 degrees, with the door arm connected to the door, place the door in the closed position, tighten shaft retaining bolt to 25 ft .lbs.

4. For pair applications - repeat process for secondary operator beginning at step 2.
5. Adjusting Open door stop

Determine opening angle required for application adjust internal stop accordingly.

(1)

An external door stop may be needed depending on application (abuse, excessive wind ).

Proceed to page 30

## Commissioning with FCP

## Commissioning

1. Apply primary power to the operator, for pair of doors apply power to the Primary operator first, then to the Secondary operator.

2. Commissioning - Enter Code 021 Start commissioning, for pairs complete primary operator sequence first.
3. Door will automatically open and hold open at 20 degrees.

4. Exit Preload - Enter Code 020 door closes.
5. Door will automatically begin opening until the open door stop is reached, door will immediately close.(Checking door weight/ momentum)

6. Escalating 6 tones will occur before door begins opening. (Door mounted safety sensor inhibiting)

7. For pair applications, repeat sequence for secondary operator, begin at step 2. Primary operator will go to the open position until commissioning is completed.

## Additional Adjustments

Additional adjustments may need to be made after commissioning. Listed below are the most common adjustments. For additional adjustments refer to the Programming Charts.
*Hold open time = Code 10?
*Push-N-Go OFF = Code 860
*Close Check Force OFF = Code 320
**Power Close for Lock Release ON = Code 581
**Delay Time to Open = Code 591
Power Pulse when Opening = Code 43? Over come wind stack pressure
*Double egress/ simultanious pairs = Code 830
Turn OFF delayed activation of secondary operator for pair applications.
Detecting/ mask out safety functions details on page 31 = Code 023
Power Assist in AUTO ON = Code 862
Power Assist Hold open Time = Code 150
Repeat commissioning without system values details on page 31.
On-Board Button $=$ Code 6

* Adjustments have been changed by entering Country code 7.
** Adjustment 591 needs to be made in conjunction with 581.


## Testing

Test the door in accordance with ANSI A156.19 Power Assist and Low Energy Power Operated Doors or ANSI A156.10 Power Operated Pedestrian Doors standards before putting the door into service and handing it over to the End-User.

## Code Descriptions/ BDM LED Displays

## Country Code

The Country code is available in firmware V3.02 and above. The country code provides preset values to aid the technician in installing the door to comply with ANSI Standard A156.19. Country code can be set with On-board button Code $7 / 1$ or FCP code 031. To remove the country code adjustments perform a factory reset. Functions changed are listed below:

| Hold Open Time=105 | Opening Speed=203 | Closing Speed=214 |
| :--- | :--- | :--- |
| Closing Force=311 | Close Check Force $=320$ | Safety Function BDM IN4=602 |
| Safety Function PDM IN4=651 | Pair without Overlap=830 | Push N Go OFF=860 |

## Detecting safety features (optional)

If the safety sensors in the opening and/or closing direction were not detected correctly or have been connected for the first time, they can be subsequently detected. Detect and save safety features 1-2

Code 3 on-board configuration (FCP code = 023 )

| Procedure according to Code 023 or OB Code 3 | Conditions | Result |
| :---: | :---: | :---: |
| Waiting time 5 seconds (rising motor signal tone). The safety sensor connection type is detected. The door opens and closes again. <br> After the door reaches the open position, the number of testable safety sensors is indicated by the number of times the green LED ( $0-2$ times). | Sensors must be correctly connected. Do not enter the detection area of the moving safety sensors. | If the testing of the safety feature "open" is successful, the door opens at full power.If the testing of the safety feature "close" is successful, the door closes at full power. The safety feature "open" is automatically suppressed if the door moves against a wall. |

## Repeat commissioning (without system values)

If the door arm or shaft position was changed or glass was installed in the door after commissioning.

Code 6 on-board configuration

| Procedure according to OB Code 6 | Conditions | Result |
| :--- | :--- | :--- |
| Operator rotates $20^{\circ}$, beeps 2x, Press \& Release the <br> OB button, operator will close slowly, automatically <br> opens slowly \& fully open \& beeps 2X, close (beep <br> 1x) followed by 5 beeps. and will fully open \& close <br> at normal speed. | Door travel path un- <br> obstructed, no physical <br> contact with the door <br> during the learn cycles. <br> Minimal wind load. | Door open \& closed positions detected. Door <br> weight detected. <br> Safety functions detection according to Code 023, <br> OB Code 3. |

## Displays

Troubleshooting codes displays as E/H on the user interface. See the Troubleshooting Codes Chart in this manual for their meaning.
LED displays on the base door module BDM

| Yellow LED off | OK |
| :--- | :--- |
| Yellow LED on | Error (E). See the user interface or Skipper for the error display. <br> See the Trouble shooting chart in this manual. |
| Green LED on | Power supply and module OK |
| Green LED off | No power supply or power supply overloaded. |
| Green LED flashes | A programming step was started via the on-board programming button. <br> The process is on going. Press the button briefly to stop the process. |
| The Green LED flashes | $0 \times=$ No testable safety feature available. Door moves with low energy. <br> after the open position is <br> reached |

## Programming Table

| Cod |  | Function |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | UR Door operator type 1102 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Remains after factory reset |
| 01 | 2 | UR Door operator type 1201 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Remains after factory reset |
| 02 | 0 | End procedure "Spring preload" |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 02 | 1 | Start commissioning |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Only possible after entering system parameters 06x, 07x, 08x |
| 02 | 2 | Start Teach-In |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 02 | 3 | Detecting and storing of safety functions |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Safety functions on terminals in3+4 PDM" and in4 BDM |
| 02 | 4 | Delete registration of unplugged modules MDM, PDM, EDM |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | The modules will be registered automatically at power-up |
| 03 | 1 | Preset 1=Handicap Function (=OB code 7/1) (=P105,203,214,311,320,602,651,830,860,870) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Reverse with factory reset |
|  | 0 | UR Reset |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Starts program with calibration run |
| 04 | 1 | Factory Reset |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | All adjustments back to default values (see *) |
| 04 | 2 | UR Display firmware version |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: $\mathrm{r06}$-00 = V06.00 |
| 04 | 3 | UR Display number of cycles |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: c10_302 = 10'302 cycles (max. 99?999?999) |
| 04 | 4 | UR Display number of operating hours |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: h4_002 = 4002 hours (max.99'999'999) |
| 04 | 5 | Delete fault protocol |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 05 | 0 | Display registration module EDM |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | A0 =not registered, A 1 =registered |
| 05 | 1 | Display registration module PDM |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | A0 =not registered, A 1 =registered |
| 05 | 2 | Display registration module MDM |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | A0 =not registered, A1 =MDM-A registered, A2 =MDM-B registered |
| 05 | 3 | Display registration secondary door operator |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | A0 =Single door, A1 =primary door, A2 =secundary door |
| 05 | 4 | Display voltage intermediate circuit 40VDC |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: u22_8 = 22,8V |
| 05 | 5 | Display voltage 24VDC supply |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: u22_8 $=22,8 \mathrm{~V}$ |
| 05 | 8 | Display temperature transformer (calculated) (from FW V03.10) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: t39_5 $=39,5$ degree C |
| 05 | 9 | Display temperature motor (calculated) (from FW V03.10) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Example: $\mathrm{t} 39 \_5=39,5$ degree C |
|  | 1... 8 | Door width (=OB code 1/1) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 0 * | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |  |  |  |  |  |  |  | code |
|  |  | 0 | 28" | 32" | $36 "$ | 40" | 44" | $48^{\prime \prime}$ | 52" | 56" |  |  |  |  |  |  |  | inches |
|  | 1... 6 | Reveal (=OB code 1/2) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 0* | 1 | 2 | 3 | 4 | 5 |  | 6 |  |  |  |  |  |  |  |  | code |
|  |  | 0 | 1-2" | 2-4" | 4-6" | 6-8.5" | 8.5-10.5 | .5" 10.5 | -12.5" |  |  |  |  |  |  |  |  | inches |
| 08 1...6 |  | Drive Arm Length (=OB code 1/3) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 0* | 1 | 2 | 3 | 3 | 4 | 5 | 6 |  |  |  |  |  |  |  |  | code |
|  |  | 0 | 11-3/8 | Cus | m 13-3 | 3/4"\|13 | 3-3/4" ${ }^{\text {c }}$ | Custom | Custom |  |  |  |  |  |  |  |  | inches (Out-Swing Arm/ Push 1,2,3) (In-Swing Arm/ Pull 4,5,6) |
| $090 \ldots 9$ |  | Spring tension (=OB code 4) ONLY APPLIES to 1201 Operator |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 1* | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |  |  |  |  |  |  |  |  |
|  |  | 0 | 5 | 10 | 15 | 20 | 25 | 30 | 35 | 40 |  |  |  |  |  |  |  | mm |
| 10 0...F |  | UP Hold-open time for Auto Mode |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Is also determined by the teach-in. |
|  |  | 0 | 1* | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | A | b | C | d | E | F | code |
|  |  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 15 | 20 | 40 | 60 | >/> | sec. (>/>=step control) |
| $110 \ldots \mathrm{~F}$ |  | UP Hold-open time of activator for Beds |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 * | 9 | A | b | C | d | E | F | code |
|  |  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 15 | 20 | 40 | 60 | >/> | sec. (>/>=step control) |
| $120 \ldots \mathrm{~F}$ |  | UP Key Switch Hold-open time |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 0 | 1 | 2 | 3* | 4 | 5 | 6 | 7 | 8 | 9 | A | b | c | d | E | F | code |
|  |  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 15 | 20 | 40 | 60 | >/> | sec. (>1>=step control) |
| $130 . . .9$ |  | UP Delay time Mode of op. OFF |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 0 | 1 | 2 * | 3 | 4 | 5 | 6 | 7 | 8 | 9 |  |  |  |  |  |  | code |
|  |  | 1 | 3 | 5 | 7.5 | 10 | 15 | 20 | 30 | 45 | 60 |  |  |  |  |  |  | sec. |
| $140 \ldots 9$ |  | UP out3 EDM: Bell active time |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 0 = Off |
|  |  | 0 | 1 | 2 * | 3 | 4 | 5 | 6 | 7 | 8 | 9 |  |  |  |  |  |  | code |
|  |  | 0 | 0.5 | 1 | 2 | 3 | 4 | 5 | 6 | 8 | 10 |  |  |  |  |  |  | sec. |
| $150 . .9$ |  | Power Assist Hold- open time after opening |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 0 = Off |
|  |  | 0 | 1* | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | A | b | C | d | E | F | code |
|  |  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 8 | 10 | 12.5 | 15 | 17.5 | 20 | 40 | 60 | >> | sec. |
| UP=(P) Program mode. UR=(R) Read parameter mode * = Default value |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

## Programming Table



## Programming Table



UP=(P) Program mode. UR=(R) Read parameter mode

* $=$ Default value


## Programming Table



## Troubleshooting Codes

* E = Error | H = Hint

| * No. | Fault | Behaviour of System | Reset |
| :---: | :---: | :---: | :---: |
| E0x | Internal test negative. Fatal error. | Safety operating | Power OFF-ON. Possibly press button 5s |
| E11 | Motorised lock not unlocked | Door blocked | Automatically if OK |
| E12 | Motorised lock not locked |  | Automatically if OK |
| E23 | CAN connection EDM interrupted | Safety operating mode |  |
| E24 | CAN connection PDM interrupted | Safety operating mode |  |
| E25 | CAN connection MDM interrupted | Safety operating mode |  |
| E26 | CAN connection primary - second. interrupted | Primary continues, second. stays closed |  |
| E31 | Safety open > 1 min. active, test neg. | According safety function | Automatically if OK |
| E32 | Safety closing > 1 min . active, test neg. | According safety function | Automatically if OK |
| E33 | Safety stop > 1 min . active, test neg. | According safety function | Automatically if OK |
| E34 | Safety swing area > 1 min. active, test neg. | According safety function | Automatically if OK |
| E35 | Safety open creep > 1 min . active, test neg. | According safety function | Automatically if OK |
| E36 | Safety close creep > 1 min . active, test neg. | According safety function | Automatically if OK |
| E37 | Safety open Low En. > 1min. active, test neg. | According safety function | Automatically if OK |
| E38 | Safety clos. Low En. >1min. active, test neg. | According safety function | Automatically if OK |
| E41 | Activator inside > 1min. active | Door remains open | Automatically if OK |
| E42 | Activator outside > 1min. active | Door remains open | Automatically if OK |
| E43 | Key switch > 1min. active | Door remains open | Automatically if OK |
| E45 | Emergency open > 1 min . active | Door remains open | Automatically if OK |
| E46 | Emergency close $>1 \mathrm{~min}$. active | Door closes and remains closed | Automatically if OK. |
| E47 | Inhibit switch > 1 min. active | Door closes without hold open time | Automatically if OK. |
| E48 | Activator bed passage > 1min. active | Door remains open | Automatically if OK |
| E51 | Encoder not working | Safety operating mode | Reset |
| E61 | Power supply 40V outside of admissible range | Safety operating mode | Automatically if OK |
| E62 | Power Supply 24V outside of permissible range | Safety op. mode | Automatically if OK |
| E63 | Power Supply 24V short circuit | Safety op. mode | Automatically after 20s if OK |
| E64 | Motor hot | Safety operating mode | Automatically after cooling down |
| E66 | Motor faulty. Interruption of motor control. | Safety operating mode. No braking! | Replace motor |
| E68 | Power failure (Power on) |  |  |
| E99 | Error at secondary drive unit |  |  |
| H01 | System was started | Safety op. mode | Reset |
| H02 | Factory reset required (VEE unreadable) | Safety mode | Factory reset |
| H11 | Parameter 06... not yet programmed | Safety operation | Enter parameter |
| H12 | Parameter 07... not yet programmed | Safety operation | Enter parameter |
| H13 | Parameter 08... not yet programmed | Safety operation | Enter parameter |
| H14 | Commissioning not executed | Safety operation | Start commissioning |
| H15 | Timeout moving. Door blocked. Motor faulty | Commissioning is canceled | Restart commissioning |
| H16 | Mass detection faulty (wind, opening angle) | Autom. detection is terminated | Restart automatic detection |
| H17 | Open endstop too soft. Motor may overheat |  |  |
| H18 | Safety function is used more than once |  | See P60x, P64x, P65x |
| H19 | Detection of safety functions pending |  | P023 or OB code 3 |
| H21 | Teach-In: Door moves >25 s before start | Abort Teach-In | New Teach-In |
| H22 | Teach-In: No start within 60s | Abort Teach-In | New Teach-In |
| H23 | Teach-In: Movement to slow. >60 s | Abort Teach-In | New Teach-In |
| H31 | Obstacle detection at opening | Door reverses | Automatically, Display 20s. |
| H32 | Obstacle detected at closing | Door reverses | Automatically, Display 20s. |
| H33 | Permanent obstacle at opening | Safety operation | Reset |
| H34 | Permanent obstacle at closing | Safety operation | Reset |
| H46 | FW missmatch in primary and secondary |  |  |
| H62 | Calibration run in closing direction | Searches closed position | At the end of movement |
| H67 | Absolute position not found yet | Slow opening movement |  |
| H71 | Battery mode | Door moves slowly | Power supply return |
| H74 | Motor current in open position too high | E64 can trigger later | P404. Avoid wind load. Install HM |

## Control Connection Diagram

Connect components only with primary power removed (current-less).
Terminal Allocation in Default Programming


## Exterior Door Module (EDM)



## Multi Door Module (MDM -B)



## Multi Door Module (MDM -A) - (Non Stocking part, special order)



1) Function programmable
2) OUT 1A \& OUT 1B are Normally Open dry contact Load on power supply 24 VDC max. 1.5 A/36 W

## Connection Diagram





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| :---: | :---: |
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## Connection Diagram

## Connection Diagram

| z0 :\# uois!ıəə | 800 Lozl :\# Su!Mexa |
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| Waつ :Kq pes!^əบ | LL/6z/8: əıе |
|  |  |
|  <br>  |  |
|  |  <br> 'Ju\| $\forall$ Sn XVWyO1 |



## Connection Diagram



## Connection Diagram



## Connection Diagram



## Connection Diagram



$\begin{aligned} & \text { 2) Reference 1201/1102 Installation \& Service manual for details of dual operator installation and commissioning. } \\ & \text { 3) Enter Code } 602 \text { to program IN4 for Safety Closing with Reversing Function. } \\ & \text { 4) Adjust operator and sensors to be in accordance with ANSI A156.19. }\end{aligned}$
$\begin{array}{r}\text { Məəə ( } \\ : \exists \perp O N\end{array}$


## Connection Diagram



| 8 | G | 9 | $L$ | （ヨดIS 77nd）N＊OSษヨdกS |
| :---: | :---: | :---: | :---: | :---: |
| 否 |  | $\frac{\bar{Z}}{\bar{\lambda}}$ | 罰 | $\text { (ヨaIs רากd) ヨ૭ロヨ - } \forall \text { ) }$ |





## Connection Diagram



## TECHNICAL SPECIFICATIONS

| 1000009 | Mechanical Documentation <br> Shaft Removal | AUTOMATIC <br> 12859 Wetmore Road San Antonio, TX 78247 WWW.TORMAXUSA.COM |
| :---: | :---: | :---: |
| Area of application | iMotion 1301, 1201, 1102 Swing Door Operator |  |
| Release | August 2016 |  |
| Use | Technician Reference |  |

## Purpose

Provide guidance in the removal of the drive arm shaft for a 1301,1201, 1102 operator. Removal of the shaft will require the extraction bolt part\# US801643.

## Removal

1. Remove power from the operator, remove the arm assembly from the shaft.
2. Remove the shaft retaining bolt part\# US801528 as shown in illustration \#1.
3. Insert the shaft extraction bolt into the operator \& shaft as shown in illustration \#2
4. Using a 6 mm hex head allen wrench turn the bolt in a clockwise direction, screwing in the extraction bolt. The bolt pushes the shaft out of the operator as shown in illustration \#3.


## TECHNICAL SPECIFICATIONS

## T1253e Cable Plan



| No. | Control Components | Notes | Cable | Length (ft) without screen | Length (ft) with screen |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Activator/Push-button inside | Stranded wire recommended | $4 \times 20$ AWG | < 98 | < 328 |
| 2 | Activator/Push-button outside | Stranded wire recommended | $4 \times 20$ AWG | < 98 | < 328 |
| 3 | Key-switch | Stranded wire recommended | $2 \times 20$ AWG | <98 | < 328 |
| 4 | Input | Stranded wire recommended | ... $\times 20$ AWG |  | < 328 |
| 5 | User interface iMotion Connected with FCC-connector |  | Phone ribbon cable $6 \times 014 \mathrm{~mm}{ }^{2}$ <br> RJ12,6P,6C | < 98 |  |
|  | User interface iMotion Connected with LIN-Adapter |  | $3 \times 0,25 \mathrm{~mm}^{2}$ | <98 | < 100 |
| 6 | Safety activator closing |  | $4 \times 20$ AWG | <98 | < 328 |
| 7 | Safety activator opening | Stranded wire recommended | $4 \times 20$ AWG | <98 | < 328 |
| 8 |  |  |  |  |  |
| 9 | Door lock | Stranded wire recommended | $4 \times 20$ AWG | < 82 | < 328 |
| 10 | Message $1 . .$. | Stranded wire recommended | $2 \times 20$ AWG | <98 | < 328 |
| 11 | Message $2 . .$. | Stranded wire recommended | $2 \times 20$ AWG | <98 | < 328 |
| 12 | Mains main switch |  | $3 \times 14$ AWG |  |  |

## TECHNICAL SPECIFICATIONS

T-1633e 1201 Technical Information

| Drive type | TORMAX 1201 Swing Door Drive |
| :---: | :---: |
| Drive system | Electro-mechanical drive with DC-motor, extensible with modules, spring activated closing or opening. |
| Control System | MCU42 |
| Door leaf width and mass | $28^{\prime \prime}-56$ ", up to 551 lbs . according to diagram |
|  |  |
| Opening angle | $70^{\circ} \ldots 110^{\circ}$ max. |
| Speed | $5^{\circ} \ldots 60 \%$ max. |
| Mains connection | 230/115 VAC, $50 / 60 \mathrm{~Hz}$ |
| Dimensions | $3-11 / 32^{\prime \prime} \times 5-3 / 64 " \times 25-13 / 64 "$ <br> 2 leaves with mechanical door coordinator: $100 \times 135 \times$ door width |
| Power consumption | 3 ... 200 W |
| Automatic reset in the event of a power failure | In the closing and opening direction; capable of an infinitely variable setting: 60100 \% of maximum force according to DIN 1154 corresponds to closer parameter $4-6$ with the linkage pushing and closer parameter 3 when the linkage is pulling. |
| Protective class | IP 20 |
| Ambient temperature | $-68 \ldots 122^{\circ} \mathrm{F}$ |
| Weight: | 26 lbs |
| Emitted noise level | $<70 \mathrm{dBA}$ |
| Sensor supply | 24 VDC (+0.5-1.5 V) Pmax. 36 W, Imax. 1.5 A |
| Inputs | 24 VDC or potential-free (Multi Door Module MDM-A) |
| Outputs | Holding magnet 24 VDC, <0.25 A (Exterior Door Module EDM) Bell 24 VDC, $<1$ A, (Exterior Door Module EDM) El. door opener 24 VDC, < 1 A, (Exterior Door Module EDM) Potential-free 24 VDC, $<1$ A, (Multi Door Module MDM-A) Test-out 24 VDC, < 1 A, (Power Door Module PDM) |
| Interfaces | CAN for double door and air lock (MDM-A/MDM-B) <br> RS232 for Skipper (EDM, Programming Interface Module PIM) RS485 (MDM-A) <br> LIN-Bus (EDM, Programming Interface Module PIM)) |
| Approvals and standards | CE <br> EN 16005 (TÜV) <br> UL 325 <br> UL 228 <br> EN 61000-6-2, EN 61000-6-3, EN 60335-1 |
| Durability | DIN 18650 (TÜV) - 1 Million test cycles at 4000 cycles per day |

## TECHNICAL SPECIFICATIONS

## T-1634e 1102 Technical Information



## TECHNICAL SPECIFICATIONS

## Electrical Requirements for Installation Personnel

## Have a licensed electrician:

- Make all mains primary power connections in accordance to federal, state and local regulations.
- Route mains primary power from power distribution panel (10 amp circuit breaker minimum per operator) to the operator.
- Install a service switch or emergency shut OFF switch, if required by customer or per regulations. This is in addition to the mains circuit breaker to interrupt power, switch must be rated @ 10 amp minimum.


## Mains Connection

Connection: N + L1 + PE protected on site with 10 AT, protective earth necessary
Power rating: $1 \times 230 / 1 \times 115$ V AC (+5 \%/ - $10 \%$ ) $50-60 \mathrm{~Hz}$, max. 200 W
Supply cable: Type H05VV-F, H05RR-F or flexible cord of type S, SO, SJ, SJO, ST, STO, SJT, SJTO or AFS


Before beginning the work described below, check that the mains primary power is switched off. If required place "Out of Service" tag on circuit breaker or service switch.

- Route the mains connection to the operator along the side of the power supply.
- The edges must be rounded off on all bushings for the mains connection.
- Route mains cable either through the header end cap or through header back plate.
- Use only cable bushings made from synthetic materials Metallic bushings must be grounded.
- Connect mains cable to terminal (1) as shown in the illustration.

- Secure mains cable with a cable strap at a synthetic lug on the base plate.
- Do not apply power to the door until ready for commissioning.
- A system switch (FCP or 3-position switch) must be on site.

Secure mains cable properly to prevent it from getting into the moving parts of the operator or door system.

## TECHNICAL SPECIFICATIONS

| T-1753 e | Application <br> Double Door Hospital | TORMAK <br> AUTOMATIC |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive | 12859 Wetmore Road |
| Release | 10 October 2014 | 1-888-685-3707 www.tormaxusa.com |
| Use | Planning, installation, maintenance |  |

The purpose of the application is to coordinate double-leaved doors using Type 1201 or 1102 swing door drives with each other in such a manner that non-overlapping double doors open at the same time as each other and that overlapping double doors open with a brief time interval between each leaf and close in the right order. Fire doors may only be operated with the proven mechanical door coordinator system MDC.


## Door Opening Sequence

Movement without overlapping (P830). Synchronous
When an opening command is given both door leaves start to open at the same time. The door leaves move independently of each other according to a pre-set motional sequence.
At the end of the hold-open time on the primary leaf (commences as soon as both door leaves have reached the open position), both leaves begin to close independently of each other according to a pre-set motional sequence.
Reverse commands are transmitted to both drives. However, an obstruction on opening only affects the door leaf encountering the obstruction.

Movement with overlapping (P831, P832). Asynchronous
When an opening command is given the primary leaf starts to open. When an opening angle of 7 degrees is reached, the secondary leaf starts to open. The door leaves move independently of each other according to a pre-set motional sequence. At the end of the hold-open time on the primary leaf (commences as soon as both door leaves have reached the open position) both leaves begin to close independently of each other according to a pre-set motional sequence.
The primary leaf then stands still at an angle of 10 degrees / 40 degrees (P831, P832) and waits in this position until the secondary leaf is completely closed. The primary leaf does not close until the secondary leaf is completely closed.
Reverse commands are transmitted to both drives.

## Operating Mode Control and Operation

The operating modes and the reset function are entered on the primary drive. These then apply automatically for both drives. Single leaf operation is entered on the secondary leaf.

## TECHNICAL SPECIFICATIONS

## Connection

See T-1688 for cable diagram for double-leaf system


## TECHNICAL SPECIFICATIONS

| T-1637 e | Module Documentation <br> Base Door Module MCU42-BDM-A | $\star \star \star \star \star$ TORMAX <br> AUTOMATIC 12859 Wetmore Road San Antonio, Tx 78247 1-888-685-3707 www.tormaxusa.com |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive |  |
| Release | 22 December 2014 |  |
| Use | Planning, installation, maintenance |  |

## Purpose

Central control component for the TORMAX 1102 and 1201 swing door drives.

## Function

The base door module (BDM) provides all the essential basic functions for the operation of a swing door system (see also installation overview T-1660). Additional functions and interfaces can be added with the additional modules (EDM, PDM, MDM). The BDM and additional modules communicate with each other via the internal CAN-BUS. The BDM is able to recognize the additional modules automatically via the CAN-BUS after their connection and then to initialize/configure them appropriately.


If the module is touched it must be protected against electrostatic discharge (ESD). Other components must not be touched.

- Only connect the basic module (8) and secure it to the points provided when the power is switched off. - Do not switch on the power until any additional MCU4 modules (10) which are required are connected.
- Place the cover plate (9) in position.


3 Additional modules EDM, PDM, MDM, PIM

## TECHNICAL SPECIFICATIONS

## Module Connections

The additional modules EDM, PDM, MDM may be arranged in any order. The programming interface module PIM can be connected at the end of the row. Standard assignment for terminal connections - see T-1655.


## Commissioning

The system may be configured either by means of the on-board configuration tool (SW1 and LEDs) or the MCU32-USIN-7 user interface or iMotion Skipper software.
iMotion Skipper is used for firmware updates (see TORMAX Extranet). Firmware updates install the latest software versions on the modules which are connected.
Programming using the user interface - see T-1248.

## Technical Data

| Processor: | 32 bit, 100 MHz |
| :--- | :--- |
| System monitoring: | Complies with the requirements of DIN 18650 |
| Ambient temperature: | $-4 \ldots+122{ }^{\circ} \mathrm{F}$ |
| Over temperature protection: | $+167^{\circ} \mathrm{F}$ |
| Dimensions: | $2.519^{\prime \prime} \times 3.858^{\prime \prime}$ |
|  | max. load 1 amp (at $68{ }^{\circ} \mathrm{F}$ ) |
| Output OUT 1: | Thermal overload protection, slef resetting |
|  |  |
| Inputs IN 1-4: | 24 VDC / 3mA pull up |
| Serial interfaces: | $1 \times$ CAN (internal) |
|  | $1 \times$ LIN (connection only via EDM or PIM) |
|  | $1 \times$ RS485 (connection only via MDM) |
|  | $1 \times R S 232$ (connection only via EDM or PIM) |
| Module interfaces: |  |
|  | MCU42-EDM-A (T-1638) |
|  | MCU42-PDM-A (T-1639) |
|  | MCU42-MDM-A (T-1640) |
|  | MCU42-MDM-B (T-1640) |
|  | MCU42-PIM-A (T-1691) |

## TECHNICAL SPECIFICATIONS

| T-1638 e | Module Documentation <br> Exterior Door Module MCU42-EDM-A | $\star \star \star \star \star$ TORMAX |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive | 12859 Wetmore Road |
| Release | 9 January 2015 | www.tormaxusa.com |
| Use | Planning, installation, maintenance |  |

## Purpose

Additional module for the TORMAX 1102 and 1201 Swing Door Drive for external doors.

## Function

The exterior door module (EDM) contains all connections needed for an external door. The inputs and outputs which supplement the BDM are not programmable.

External door module MCU42-EDM-A


1 Connector plugs for additional modules
2 Inputs (IGA: external activator, SS: key switch)
3 Outputs (OUT2: holding magnet, OUT3: bell)
4 Output OUT1 potential-free (door opener, motor lock), Input IN1 (motor lock feed-back)
5 RS232 (Skipper)
6 LIN (user interface)
7 Status display

## Installation

$\triangle$
The module must be protected against electrostatic discharge (ESD) when touching it. Other components must not be touched.

- Only plug in the module and secure it to the
points provided when the power is switched off



## TECHNICAL SPECIFICATIONS

## Module Connections

The additional modules EDM, PDM, MDM may be arranged in any order. Standard assignment for terminal connections see T-1655.
Base Door Module
BDM
MCU42-BDM-A

## Commissioning

The module is automatically recognized by the basic module BDM as soon as the power is switched on. The LED status display is illuminated when the module is ready for operation.

## Technical Data

| Processor: | 32 bit, 100 MHz |
| :---: | :---: |
| System monitoring: | Complies with the requirements of DIN 18650 |
| Ambient temperature: | $-4 \ldots+122{ }^{\circ} \mathrm{F}$ |
| Dimensions: | $2.519^{\prime \prime} \times 2.519^{\prime \prime}$ |
| Outputs OUT 2-3: | max. load $1 \mathrm{~A}\left(\right.$ at $68{ }^{\circ} \mathrm{F}$ ) <br> Thermal overland protection, self resetting |
| Outputs OUT 1 A/B: | Potential-free <br> max. load 1 A (at $68^{\circ} \mathrm{F}$ ) <br> Thermal overland protection, self resetting <br> Voltage max. 40 VDC/ 30 VAC <br> Potential relative to earth max. 75 VDC/ 50 VAC |
| GNDct: | max. load 1 A (at $68{ }^{\circ} \mathrm{F}$ ) <br> Thermal overload protection, self resetting |
| Inputs IN 1/SS/IGA: | $24 \mathrm{VDC/} 3 \mathrm{~mA}$. pull up |
| Serial interfaces: | $1 \times \mathrm{CAN}$ (internal) |
| Module interfaces: | $1 \times \mathrm{LIN}$ |
|  | $1 \times \mathrm{RS} 232$ (Skipper) |
|  | MCU42-BDM-A (T-1637) <br> MCU42-PDM-A (T-1639) <br> MCU42-MDM-A (T-1640) <br> MCU42-MDM-B (T-1640) |

TECHNICAL SPECIFICATIONS

| T-1640 e | Module Documentation <br> Multi Door Module MCU42-MDM-A /B | $\star \star \star \star \star$ <br> TORMAX <br> AUTOMATIC 12859 Wetmore Road San Antonio, Tx 78247 1-888-685-3707 www.tormaxusa.com |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive |  |
| Release | 9 January 2015 |  |
| Use | Planning, installation, maintenance |  |

## Purpose

Additional module for the TORMAX 1102 and 1201 swing door drives for operating double leaved doors or air locks. The module is also used for networking via RS485 or if additional potential-free inputs and outputs become necessary.

## Function

In the case of double doors and/or air locks, communication between the drives is via the CAN-BUS on the MDM.


Installation

$\triangle$
If the module is touched it must be protected against electrostatic discharge (ESD).
Other components must not be touched.


## TECHNICAL SPECIFICATIONS

## Module Connections

The additional modules EDM, PDM, MDM may be arranged in any order. Standard assignment for terminal connections see T-1655.


T1637_2e

Potential-free inputs


## Potential-free outputs

| $\begin{aligned} & \text { OUT } \\ & \text { A B } \end{aligned}$ |
| :---: |
| 0 |
| 00 |
| $\otimes$ |
| External supply |
| $\leq 40$ VDC |
| $\leq 30$ VAC |
| $<1$ A |

Circuit diagram


## Commissioning

The module is automatically recognised by the basic module BDM as soon as the power is switched on. The LED status display is illuminated when the module is ready for operation.

## Technical Data

| Processor: | 32 bit, 100 MHz |
| :---: | :---: |
| System monitoring: | Complies with the requirements of DIN 18650 |
| Ambient temperature: | $-4 \ldots+122{ }^{\circ} \mathrm{F}$ |
| Dimensions: | $2.519^{\prime \prime} \times 2.519^{\prime \prime}$ |
| CAN ext.: | CAN open, $125 \mathrm{kbit} / \mathrm{s}, 500 \mathrm{~m}$ in a line (max. 22 m from transmission line) |
| RS485: | For details see T-1531 (RS485-network) |
| Outputs OUT 1-4 A/B: | Potential-free, max. load 1 A (at $-4^{\circ} \mathrm{F}$ ), Thermal overload protection, self resetting Voltage max. 40 VDC / 30 VAC, Potential relative to earth max. 24 VDC/ 50VAC |
| Inputs IN 1-2: | $24 \mathrm{VDC} / 3 \mathrm{~mA}$ Pull up, Potential-free, Signal source 10-30 VDC |
| Inputs IN 3-4 A/B: | Potential relative to earth max. $75 \mathrm{VDC/} 50 \mathrm{VAC}$ |
| Module interfaces: | MCU42-BDM-A (T-1637) |
|  | MCU42-EDM-A (T-1638) |
|  | MCU42-PDM-A (T-1639) |
|  | MCU42-PIM-A (T-1691) |

## TECHNICAL SPECIFICATIONS

| T-1639 e | Module Documentation <br> Power Door Module MCU42-PDM-A | $\star \star \star \star \star$ TORMAX |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive | 12859 Wetmore Road |
| Release | 7 January 2015 | 1-888-685-3707 www.tormaxusa.com |
| Use | Planning, installation, maintenance |  |

## Purpose

Additional module for the TORMAX 1102 and 1201 swing door drive for full energy operation.

## Function

Two testable safety features can be connected to the PDM. If a testable safety feature is recognised when the door is opening, the door is automatically opened at full power. If a testable safety feature is recognised in the closing direction, the door is automatically closed at full power. The door moves at low power if there are no testable working safety features.

Power Module MCU42-PDM-A


1 Additional module connecting plug
2 Inputs

- IN1: emergency movement
- IN2: inhibit switch

3 Testable safety features

- OUT2 / IN4: S2 safety, opening
- OUT1 / IN3: S1 safety, closing

4 Status display

## Installation

$\triangle$
If the module is touched it must be protected against electrostatic discharge (ESD). Other components must not be touched.

- Only plug in the module and secure it to the points provided when the power is switched off.



## TECHNICAL SPECIFICATIONS

## Module Connections

The additional modules EDM, PDM, MDM may be arranged in any order. Standard assignment for terminal connections see T-1655.


## Commissioning

The module is automatically recognised by the basic module BDM as soon as the power is switched on. The LED status display is illuminated when the module is ready for operation.

## Technical Data

| Processor: | 32 bit, 100 MHz |
| :--- | :--- |
| System monitoring: | Complies with the requirements of DIN 18650 |
| Ambient temperature: | $-4 \ldots+122{ }^{\circ} \mathrm{F}$ |
| Dimensions: | $2.519^{\prime \prime} \times 2.519^{\prime \prime}$ |
| Outputs OUT 2-3: | max. load $1 \mathrm{~A}\left(\right.$ at $\left.-4{ }^{\circ} \mathrm{F}\right)$ <br>  <br> Thermal overload protection, self resetting <br> GNDct: |
|  | max. load 1 A (at $\left.-4{ }^{\circ} \mathrm{F}\right)$ |
| Inputs IN 1-4: | Thermal overload protection, self resetting |
| Module interfaces: | 24 VDC/ 3 mA Pull up |
|  | MCU42-BDM-A (T-1637) |
|  | MCU42-EDM-A (T-1638) |
|  | MCU42-MDM-A (T-1640) |
|  | MCU42-MDM-B (T-1640) |
|  | MCU42-PIM-A (T-1691) |

## TECHNICAL SPECIFICATIONS

| T-1691 e | Module Documentation <br> Programming Interface Module MCU42-PIM-A | $\star \star \star \star \star$ TORMAX AUTOMATIC |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive | 12859 Wetmore Road San Antonio, Tx 78247 |
| Release | 17 July 2014 | $\xrightarrow{1-888-685-3707}$ |
| Use | Planning, installation, maintenance |  |
| Purpose |  |  |

Additional module for the TORMAX 1102 and 1201 Swing Door Drive for programming with iMotion Skipper or with the user interface USIN-7-A.

## Function

The module is only temporarily used for programming with iMotion skipper. The module is only required if there is no exterior door module EDM installed. At the EDM the required RS232 interface is available.


1 Programming Interface Module MCU42-PIM-A
2 RS232 (Skipper)
3 LIN (user interface)
4 Securing screws
5 Connector plug


## Installation

- Plug in the module in current-free state to the base module BDM or the last installed module respectively by means of the connector plug (5).
- Lock the module with securing screws (4).


## Technical Data

| Dimensions: | $2.519^{\prime \prime} \times 2.519^{\prime \prime}$ |
| :--- | :--- |
| Serial interfaces: | $1 \times$ LIN |
|  | $1 \times$ RS232 (Skipper) |
| Module interfaces: | MCU42-BDM-A (T-1637) |
|  | MCU42-PDM-A (T-1639) |
|  | MCU42-MDM-A (T-1640) |
|  | MCU42-MDM-B (T-1640) |

## TECHNICAL SPECIFICATIONS

| T-1757 e | Module Documentation <br> User interface MCU32-USIN-7-A | $\star \star \star \star \star$ TORMAX |
| :---: | :---: | :---: |
| Area of application | TORMAX 1102, 1201 Swing Door Drive | 12859 Wetmore Road |
| Release | 15 August 2014 | 1-888-685-3707 www.tormaxusa.com |
| Use | Planning, installation, maintenance |  |

## Purpose

Operation and programming of automatic doors with MCU32 and MCU42 Swing Door Drives.

## Function



Connection Diagram
User interface


## TECHNICAL SPECIFICATIONS

## Installation

Mounting Frame
Switch on primary power at the operator after the user interface is connected.

- Mount the FCP user interface in the appropriate holder box system.
- Or mount FCP in the side cover.

LIN Connection
Cut to length and assemble the LIN connection cable on both ends with a FCC 6-pole plug. The polarity of the FCC-plug is not of importance.

For alternative cable connections via adapter with terminal connection see module documentation LIN-Bus adapter T-1322.


## Component Dimensions



## Technical Data

Inputs:
Terminal cross section:
LIN interface:
Length of all LIN cables:
LIN cable length between modules:

Ambient temperature:
Dimensions:
Module interface
$2 \times$ Pull up in: $24 \mathrm{VDC} / 3 \mathrm{~mA}$, function programmable
20 AWG (stranded wire)
FCC 6-Pol
< 328'
< 98' max, phone ribbon cable $6 \times 0.14 \mathrm{~mm} 2$
< 100'max, LIN-Bus-Adapter MCU32-LADP-A
$-4 \ldots+122{ }^{\circ} \mathrm{F}$
$1.7716^{\prime \prime} \times 1.7716^{\prime \prime}$, recess min. .787"
MCU42-EDM-A
MCU42-PIM-A (for commissioning and maintenance)
MCU32

# TORMAX Sliding Doors 

TORMAX Swing Doors

Sales, Installation and Service. Automatic and Manual Doors


[^0]:    Press \& Hold Programming Button, Release after 1 Green LED Flash. The operator will make 1 beep and immediately begin to flash the Yellow LED.

    PAUSE
    WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP $1 \times$, then after 3 yellow flashes, Press \& Release Programming Button

    PAUSE
    WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 2X, then after 1 yellow flashes, Press \& Release Programming Button

    PAUSE
    WHILE LOOKING AT THE YELLOW LED, WAIT FOR THE OPERATOR TO BEEP 3X, then after 1 yellow flashes, Press \& Release Programming Button

