6100 Series Swing Door Operator Installation Instructions


The manufacturer's specifications for this product require the installation to be approved by an AAADM certified inspector.
record

## 6100 Series Swing Door Operator Installation Instructions

The record-USA 6100 Operator has been carefully designed, built, and tested to provide years of service.

The life of the operator package is directly related to how carefully the installation is accomplished and how accurately the instruction s are followed. Installation of this operator package should be done by properly trained and knowledgeable in stallers with a knowled ge of local code requirements and the requirements of ANSI A156.19 Standards for Low Energy and Power Assisted Pedestrian Doors. The authorized service / in stallation dealer must perform all measurements for forces, speeds, and times to insure proper and safe operation.
record-USA is not responsible for improperly adjusted or maintained automatic doors or activation / safety systems and assumes no responsibility for damages caused by automatic door systems that have not been properly installed, tested, and adjusted.

## OWNER INFORMATION TO BE PROVIDED BY THE DISTRIBUTOR / INSTALLER

* After the installation instruct the owner on the safe operation of the door.
* Location and proper use of the power switches.
* Location of the main cutoff breaker.
* Necessary warnings not covered in general instructions.
* Owners Manual and Daily Safety Checklist.
* Phone number(s) for the local servicing dealer.
* What to do in the event that a dangerous situ ation should occur, and how to shut the doors down and call for service.

READ INSTALLATION INSTRUCTIONS BEFORE INSTALLING.
The sequence of installation and adjustment is in order, however some sections will not apply. Review this instruction manual and determine those sections that do apply. Be sure all doors swing freely and clear all objects before attaching arms.
Special attention needs to be given to installations with parallel and slide arms when an adjacent wall is perpendicular to the door frame.
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## OPERATOR HANDING IDENTIFICATION

LHR STD. ARM


RHR STD. ARM


## RH TRACK ARM



## Product Description

The record Series 6100 Swing Door Operator is a power-open, spring-close unit providing full functionality conforming to either ANSI A156.19 requirements. The self-monitoring microproces-sor-based control maintains precise regulation throughout the door open / close cycle. Two operators can be connected together in a master/slave configuration providing synchronized operation. Safety is additionally increased by the use of a redundant force limitation.


1 Adjusting screw for spring tension
2 Output Shafts for Arms \& Stop
3 Drive Unit
4 Closing Spring
5 Multifunction Pushbutton / Control
6 Terminal Blocks for I/O
7 Microprocessor Control

8 Motor Drive Circuit Board
9 Slide switch S1 (rotating direction)
10 Power Supply
11 Fuse (2.0A, 5X20mm, Slo-Blo)
12 Power Supply Circuit Board
13 On / Off / Open Rocker Switch
14 Status LED and Reset Pushbutton

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## Drive Arms

> Three types of drive arms are available:
> The Standard Arm provides the most flexibility Outswing (push) reveals to 12" Inswing (pull) reveals up to 6"

The Slide Track Arm -
Inswing (pull) reveals to 6"
Outswing (push) reveals to 3 "


> The Slide Track Arm with Offset Adapter -
> Suitable for center-pivoted doors with breakout capability; Allow double-egress installations in a common header.


An extension adapter is included with each arm assembly, connecting the drive arm to the operator output shaft. The Standard Arm is provided with a 35 mm adapter which mounts the drive arm approximately $1-1 / 8$ " below the bottom of the header. The Slide Track Arm includes a 20 mm adapter, mounting the drive arm approximately $1 / 2^{\prime \prime}$ below the bottom of the header. Optional adapters are available that will increase the distance below the header to approximately $1-3 / 4$ " ( 50 mm - P/N 9-80-0007), or approximately 3" ( 80 mm - P/N 9-80-0011). For doubleegress installations, the Double-Egress Adapter kit, 4-80-0804, includes an offset adapter for the track arm and a 50 mm adapter for the standard arm, accommodating a double-rabbet frame.

Layouts for the different arm / installation configurations are attached. Check the arm assemblies prior to unit installation and verify dimensions and clearances.

## Instructions to the Installer

This unit is to be installed and commissioned by a trained technician with knowledge of ANSI A156.10 and A156.19 Standards for Power Operated Doors, applicable local codes, and recordUSA installation recommendations.

After installation, verify the door can be opened without power applied, and the force required to open the door does not exceed 50 pounds-force ( 222 N ).

## Information to provided to the owner

The Owners Manual with training and explanation of the daily safety check.
Location of the operator control panel (On / Off / Hold Open).
Specific information pertinent to the proper operation of the installation.

## Electrical preparation

Before preparing jambs, determine the method and requirements for the electrical wiring involved and whether mats or other type of activation is used.
Power requirements - $115 \mathrm{VAC}, 60 \mathrm{~Hz}, 15 \mathrm{Amp}$ Service.
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## 6100 Series Swing Door Operator Installation Instructions

## Mechanical Installation

The door panel must move freely throughout its entire opening and closing rotation. The door frame must provide a stable base, structurally sufficient to support automatic operation. Typically the operator baseplate will overlap the door jambs by 1-1/2".

Verify the installation conditions and select the arm configuration that most closely matches the installation. As a general rule, the operator output shaft will mount 4" away from the hinge jamb, measured parallel to the closed door. The door mounted foot on a Standard arm assembly will typically mount 18 " from the hinge jamb. For Slide Track arm assemblies, the door mounted track will mount with one end located $4 "$ from the hinge jamb.
Consult the attached layout drawings for additional details.
Securely attach the unit baseplate to the door frame; Hex Head Tek Screws are included \#14 X 2" for unit mounting to door frame, and \#10 X 1-1/2" for Arm mounting to door.

Typically, the drive arm is attached to the operator with the unit in the closed position. Additionally, the arm is positioned on the splined output shaft with a slight pre-load, pushing the door against the door closed stop. The spline provides incremental adjustment of $6^{\circ}$; typically, one spline index for pre-loading is sufficient.
The drive arm is attached to the lower operator output shaft using the extension adapter supplied with the arm assembly. Consult the appropriate arm configuration for proper arm positioning on the shaft (The most common application - an outswing / push configuration using the Standard arm assembly - has the drive arm mounted to the shaft perpendicular to the closed door.) When securing the arm on the shaft, insure the extension adapter has seated properly on the shaft spline. If not seated correctly, slippage of the arm on the shaft may occur. For Track arms, install the arm with the outer end of the arm against the closed door. Do not tighten the bolt; using the arm, pull the operator open and during the slow, controlled closing, insure the splines seat correctly and tighten the 6 mm socket head bolt.
Verify all fasteners are securely tightened.

## Operator Swing Direction

If the operator does not close slowly (with either arm), the handing selection switch should be changed. It is located behind a slot in the sheet metal cover for the operator control -

With no power applied, the operator should be capable of being easily pushed open and when released, will close the door at a controlled speed.

## Closing Spring Adjustment

The closing force provided by the spring is adjustable. Do not adjust the force so low that the door will not consistently close under spring power.

On a typical 3'-0" door with a standard arm assembly, the spring closing force can be adjusted from less than 5 pounds force to more than 20 pounds force, measured at the leading edge of the door.

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## 6100 Series Swing Door Operator Installation Instructions

## Open Stop

The unit is provided with an adjustable full open stop. Rotate the door to the full open position; mount the Shaft Stop onto the upper output shaft and against the Fixed Stop. The spline of the output shaft allows indexing in $6^{\circ}$ increments.
For finer adjustment, the Fixed Stop is slightly eccentric; loosen and rotate until the desired stop location is achieved and re-tighten.


For installations where severe physical abuse may occur (such as extreme wind conditions), it is suggested a floor mounted stop be installed at full open. Additionally, the operator full open stop can be set at 100 degrees or more of opening, and program the operator to electronically stop at the 90 degree full open position. This can be accomplished by manually stopping the door at 90 degrees during a calibration run, or by reducing the opening angle under the parameter "Drive / Opening angle" (using an FPC902 Hand Terminal or a Display Control Panel).

## Power Supply Connection

Connect $115 \mathrm{VAC}, 60 \mathrm{~Hz}, 10 \mathrm{~A}$, to Power Supply terminal strip

$$
\begin{aligned}
& 115 \text { VAC "Hot" (Line) to "L" terminal; } \\
& 115 \text { VAC "Neutral" to "N" terminal }
\end{aligned}
$$

The second "L" and "N" terminals provide a convenient junction for dual operator systems.
Proper grounding must be provided for the unit. A grounding tab and screw are located adjacent to the Power Supply terminal strip.
The power supply cover must be installed after connecting
 115 VAC primary service.

The multifunction pushbutton can be used for the following functions:
1 flash of the red LED will actuate a standard open cycle (if the rocker switch is on).
3 flashes of the red LED will initiate a calibration run.

4 flashes of the red LED will initiate the parameter adjust mode of a Display Control Panel.
8 flashes of the red LED will reset the unit's parameters to factory defaults.
15-17 flashes will cause the unit to reset without affecting any of the field set parameters.


After completion of the mechanical installation and prior to adjusting the parameters, always initiate a calibration run by pressing and holding the pushbutton for 3 flashes of the red LED. This will insure proper door operation by calibrating the unit to the installation conditions.

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## Exploded view of a typical single swing unit



## Servicing the Series 6100 \& 8000 with the FPC-902 Hand Terminal

After the operator has been mechanically installed, the arms attached to the door, and 120VAC connected to the power supply, connect the FPC902 Hand Terminal to the operator control. The following sequence of screens will occur. The final screen shown below is the base point from which various settings for the operator are accessed and modified.

| AKKU | PASS |
| :--- | :--- |
| FLASH | PASS |
| EEPROM | PASS |
| RTC | PASS |
| CAN | PASS |

FPC902
Version 2.12
Feb 222010
13:30:19


Accept all parameter from the STG? presS "OK "

## STATUS SCREEN

 from STG ...This screen will indicate the current status of the operator. The center 3 lines provide the door type, operation mode (Off / Open / Automatic / Manual), and the current error code. This screen is always accessible by pressing the "STATUS" button at the bottom of the FPC 902 Hand Terminal.


The following page indicates suggested parameter configurations for a typical installation.
For a detailed description of all parameters, consult the instructions provided with the FPC902.

The following documents the suggested sequence of programming the operator:

The Series 6100 is shipped configured for a combination operation designated as "USA Low Energy". If manual operation of the door is not desired (with 115VAC power present), this should be changed to "USA", as shown in the sequence at right.

If a pair of operators are to be operated simultaneously, and only one rocker switch is to be used, it should be connected to the master control, and the slave control must be set as shown at right, allowing it to function without a rocker switch.

If automatic operation in response to pushing the door is desired (Push-ToStart), select "Miscellaneous", then "Push to Actuate" and enable by selecting "2 Normal". Note on paired units, this option must be set individually for both operators.

The unit is defaulted to include support for an automatic lock. If one is not provided, select the "Locking" parameter, then "Locking Functions", and change from "3 Always locked" to "1 Night locked" to eliminate the delay before opening.


The unit(s) are now ready to be placed into operation. Turn the control panel "on", press and hold the Control Button on the door control for 3 blinks of the adjacent LED. This will initiate a calibration cycle of the operator. After a few seconds the operator should open slowly, with a short pulse during mid-opening. It should be allowed to complete this cycle without interruption.
Note: Calibration must be performed individually on both operators of a pair.
The Series 6100 and 8000 Instructions included with the FPC-902 Terminal will have a complete listing of the screens, options, and adjustments available for this operator.

Screens Available when synchronizing two operators Both Simultaneous Pairs and Double Egress


This is automatically set by the controls upon reading the Master / Slave jumper block (J13) on the controls.

This sets the lead time and lag time between operation of the master and slave operators, useful with an overlapping astragal. When set above 0 , the Master begins opening before the slave and will stop $10^{\circ}$ before fully closed, allowing the slave to close first. When set to 0 , operation is simultaneous.


This adjusts a delay time between when the master operator begins opening and when the slave begins. Closing will not be affected. When set to 0 , operation is simultaneous.

This adjusts a delay time between when the slave operator begins closing and when the master begins closing. Opening will not be affected. When set to 0 , operation is simultaneous.

When ordered as a dual synchronized pair or a double egress, the operators are factory wired and parameters preset. If any changes are made, the following setup sequence is suggested Insure Jumper J14 is set to M1 on the master unit and set to S1 on the slave unit. Apply power to both units, then press and hold the blue Control button on the master control for 8 flashes of the red LED (reset to factory defaults). Next press and hold the Control button for 8 flashes on the slave control. Return to the master unit and press \& hold the Control button for 3 flashes of its red LED (initiate a calibration run). Finally, press \& hold the button for 3 flashes on the slave control. The units should now be configured for synchronous operation, and with the above parameters set to 0 providing simultaneous operation. Note: If only one rocker switch is used, it is to be connected to the master control, and the slave control parameter CONTROL PANEL / MECHANICAL PANEL should be set to 03 Pos. (AUTO).

| CAUTION |
| :---: | :---: |
| DOOR |
| ACTIVATE SWITCH |
| TO OPERATE |

Full Power \& Low Energy "Knowing Act" doors


Full Power Approach Side


Full Power
Non-Approach Side





Arm Configuration Inswing, Butt Hinge, 0" Reveal<br>25Sep05 DPH

Arm Configuration Inswing, Butt Hinge, 3" Reveal 25Sep05 DPH

Arm Configuration Inswing, Butt Hinge, 6" Reveal



Track Arm Configuration Outswing, Butt Hinge, 0" Reveal 25Sep05 DPH

Not recommended for heavy doors and/or abusive installations



Arm Configuration Inswing, Butt Hinge, 0" Reveal<br>25Sep05 DPH

Arm Configuration Inswing, Butt Hinge, 3" Reveal 25Sep05 DPH

Arm Configuration Inswing, Butt Hinge, 6" Reveal


Inswing, 2.75"CenterPivot, 4.5"Frame 25Sep05 DPH




CONTROL TERMINAL BLOCK CONNECTIONS

3 - Approach Sensor - Power - OV
4 - Guide Rail Beam - Power/Signal - +24V
5 - Guide Rail Beam - Signal
6 - Guide Rail Beam - Power - OV
7 - Remote Switch - Signal
8 - Header Mounted Swing Side Safety - Signal

9 - BodyGuard Data Line - Data +
10 - Door Mounted Swing Side Safety - Signal
11 - Door Mounted Sensors - Power/Signal - +24V 12 - Door Mounted Approach Side Recycle - Signal 13 - Door Mounted Sensors - Power - OV 14 - Fire Alarm Signal (Jumper to 15 if not used) 15 - Fire Alarm - +24V
16 - Door Alarm Relay - N.

17 - Door Alarm Relay - COM 18 - Door Alarm Relay - N.C. 19 - Automatic Lock Power - OV (0.5A Max.) 20 - Automatic Lock Control Relay - N.O. 21 - Automatic Lock Control Relay - COM 22 - Automatic Lock Control Relay - N.C. 23 - Automatic Lock Monitor Signal 24 - Automatic Lock Power/Signal - +24V

There are three levels of resetting an operator. To reset without changing any operating parameters, press \& hold the black reset button (next to the ON/OFF rocker switch) for 6 seconds, until relay "clicks" occur. To reset and restore typical operating parameters (speed, master/ slave, etc.), press \& hold the blue button (on the door control) for 8 flashes of the red LED. To fully reset the unit, eliminating all parameter modifications (including Series 6100/8000 setting), press \& hold the blue button on the control for 9 flashes of the red LED, then immediately remove the jumper between terminals 14 \& 15. After a full reset, the parameter "Entrance System / Door Type" must be changed from "0 Basic Operator" to "25 USA Low Energy". Additional parameters, including factory settings, will also have to be re-entered. Consult factory for additional details.

 BEA Wizard OPTEX II
RED RED GRAY POWER WHITE(F1=1) GRAY GREEN(F1=1) YELLOW POWER
RELAY
RELAY

GUIDE RAIL MOUNTED PHOTOELECTRIC BEAM

Note: For proper operation, use the harness provided with sensors to be installed All wiring should be routed away from moving parts in door operator. Power available from operator for sensors is $24 \mathrm{VDC}, 1 \mathrm{~A}$.


